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Attention-driven BI-LSTM for Robust Human Activity Recognition and Classification

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ABSTRACT

Accurate and robust Human Activity Recognition is essential for applications in surveillance, healthcare, and smart environments. However, the unpredictability and complexity of human motions provide significant challenges in obtaining the desired levels of accuracy and robustness. Conventional machine learning models, such as Decision Tree, Gaussian NB, and KNeighbors, have shown limited efficacy, with estimates of accuracy ranging from 78.3% to 89.3%. Cutting-edge techniques like as Random Forest, RBF SVC, and XGB Classifier achieve a maximum accuracy of 93.8%. We present an Attention-Driven BI-LSTM model that uses bi-directional long short-term memory networks improved with a devotion mechanism to prioritize the most important characteristics in order to overcome these constraints. The present model demonstrates exceptional performance, attaining an accuracy of 99.83%, a precision of 99.46%, a recall of 99.75%, and an F1 score of 99.85%, thereby surpassing other approaches by a substantial margin. The obtained findings validate the model's resilience and effectiveness in precisely recognizing and categorizing human actions in different fields and situations.

Keywords: *Human Activity Recognition (HAR) , Attention-Driven BI-LSTM, Machine Learning Models, Deep Learning, Classification Accuracy, Temporal Sequence Analysis.*

1. INTRODUCTION

Research in the fields of healthcare, surveillance, intelligent settings, and sports centers on human activity recognition. The primary method of mechanically identifying and classifying human actions based on data from sensors or video recordings is known as human activity recognition (HAR). Anomaly detection, security, fitness monitoring, and elder care are just a few of the many potentials uses for this technology. The potential for quick data collection from wearables, cellphones, and smart cameras to analyze human behaviors is exciting. The dimensionality of data coming from a large number of sensors, the variety and complexity of human motions, and the ambient circumstances in which activities occur are all elements that make accurate and reliable human activity identification (HAR) a tough undertaking[1].

Active Recognition of Human Activities (HAR): A lot of HAR issues have been solved using basic machine learning techniques like Decision Tree, GaussianNB, and KNeighbors. Despite their simplicity and speed, these approaches are inefficient because of their reliance on costly, manually-crafted feature engineering processes and their failure to account for temporal correlations in sequential data[2]. The complexity of real-world circumstances, where activities may include overlapping or delicate motions, makes this constraint all the more problematic. Hence, these models could only manage a reasonable level of accuracy (78.3% ~ and 89.3%) in the most recent research. Furthermore, more advanced methods that include ensemble learning and superior algorithms, such as XGB Classifier, Random Forest, and RBF SVC, significantly improve the score to 93.8%.

Deep learning offers a versatile substitute for Human Activity Recognition (HAR) that can automatically derive properties from unprocessed sensor data without the need for costly and laborious pre-processing. It is common practice to use Recurrent Neural Networks (RNNs), and Long Short-Term Memory (LSTM) networks, in particular, to learn the temporal connections in order to correctly recognize the complex activity. However, when faced with noisy data or irrelevant properties, the accuracy of these conventional LSTM models could be compromised. The BI-LSTM model improves feature capture in both past and future contexts, making it more suited for range information in activity sequences[3].

These enhancements proved that our strategy worked, but now we need to figure out how to build a HAR model that can better detect temporal correlations and zero in on more discriminative data points. The attention mechanism is required in this case[4]. In deep learning, attention algorithms have shown to be very successful in November, particularly in NLP and

picture recognition. This is because of their ability to assign varying degrees of importance to various elements of the input data[5]. The use of an attention mechanism with BI-LSTM improves the model's accuracy and possible resilience by allowing it to focus on the most critical characteristics[6].

To address these shortfalls, we provide a new attention-driven BI-LSTM model that is specifically trained to recognize and aggregate human actions with high accuracy. To identify the beginning and the end of a connection that changes over time, the current method makes use of BI-LSTM networks. It also contains an attention function to help you focus on the correct parts[7]. The attention mechanism helps distil an input sequence down to its essential parts by filtering out noise and extraneous information. An improved and more reliable method of identifying and categorizing human actions is provided by this integration, which covers everything from simple sitting or walking postures to complex motions involving several body parts[7].

Combining the feature selection powers of attention mechanisms with the sequential modelling capacity of Bidirectional Inference-based Long Short-Term Memory (BI-LSTM) networks, this paper suggests an enhancement to a popular HAR deep learning framework. This hybrid approach surpasses models trained only using supervised learning or self-supervised methods in terms of generalization, allowing the model to attain much higher accuracy than classical and previously known machine learning. We may take a more holistic view when making decisions with BI-LSTM as the model can include both past and future data on activity sequence. By directing the model's attention to more subtle changes in motion, the attention mechanism improves its ability to differentiate between seemingly identical activities[8].

Using state-of-the-art HAR datasets, we conducted computationally expensive experiments to evaluate the performance of our Attention-Driven BI-LSTM model. Experimental results show that the model achieves a flawless 99% in recall, accuracy, and precision, with an F1 score of 99.83%. Applying NumPy CNNs to these models yields better results than both basic and complex ML models, including Decision Tree, GaussianNB, KNeighbors, Random Forest, RBF SVC, and XGB Classifier [9]. The proposed model also achieves a 98.9% accuracy rate, which is far better than a traditional Bi-LSTM model and shows how much of an advantage an attention mechanism may be.

The dynamic allocation of attention is a key component of this model's attention mechanism, enabling it to zero in on the most important parts of the incoming data while simultaneously ignoring irrelevant details. Human Activity Recognition (HAR) classifies activities with this in mind since most activities have small motion variations that less complex models can miss. By offering a means to adaptively zero in on the diverse and rich character of human activities in relation to local structures, our model's attention mechanism enhances activity detection's resilience and accuracy.

Our suggested model's remarkable performance, therefore, paves the way for the integration of HAR systems into a wide variety of practical domains. The concept has use in healthcare and might be used to track patients' actions in real-time. This kind of study would provide priceless insight into their lifestyle and may reveal health issues like slips or prolonged periods of inactivity. It is our understanding that this is the first instance of a dose-dependent gradual introduction of modern versions of EM algorithms into surveillance, enabling much improved automated video analysis systems to offer better monitoring over public areas, potentially leading to increased security successes. Typically, this idea may be used in smart settings to enable the development of smart systems that adapt to human actions in a way that is both personalized and aware of its surroundings.

Developing a state-of-the-art BI-LSTM model for human activity detection via attention-driven design. Our approach achieves better classification accuracy by using the temporal modelling capabilities of BI-LSTM networks and the dynamic feature selection capability of attention techniques across different types of human activities. Additionally, this supplementary study delves into the complexity and limitations of current HAR models, illuminating how new attention-driven deep learning techniques might improve scalability and performance in practical settings. Therefore, it is a foundational step towards further development of Human Activity Recognition (HAR) and its many scientifically-based applications.

The state-of-the-art performance shown by our anticipated model emphasizes the need to use cutting-edge deep learning architectures and attention mechanisms for HAR tasks. The Attention-Driven BI-LSTM model has the ability to revolutionize human activity classification and identification thanks to its high accuracy and robustness. This will pave the way for the creation of more sophisticated systems that really understand human behavior and can rely on accurate responses[10].

So that the model offered in this article can be thoroughly reviewed and its deeper implications may be explained, this work will be broken into five pieces. The literature review is discussed in Section 2, which analyses the present methodologies and approaches utilized for human activity identification. It focuses on the inadequacies of classical and deep learning-based models. Next, we have the Attention-Driven BI-LSTM model, which delves into the detailed design of these layers, attention setting, and the rationale for their integration to enhance performance. Our experimental setup, data, and training procedures are described in full in section IV so that other researchers may replicate our study. The Results Discussion, which includes a thorough evaluation of our model's performance relative to several baseline models, will be presented in this section. This paper mentions an analysis of the advantages of the suggested model using precision-recall, accuracy, and F1-score.

Concisely summarizing the key findings, Section 5: Conclusion describes the model's contributions to the area and suggests potential follow-up research[10].

2. LITERATURE REVIEW

Modern public and private video monitoring uses distributed processing (Cob-Parro et al.). These networks can identify spatiotemporal (non-3D, 2D-spatial, and 1-temporal) features as deep-learning techniques can detect image features. High processing costs prevent real-time recognition of people or events without picture segmentation methods. On edge-computing systems, RNNs and LSMs do real-time person identification and activity recognition. It is scalable, portable, and accurate on many benchmarks, including a unique dataset sensitive to real-world deployment[11].

Sezavar et al. suggest mobile sensor-based human activity detection (2024). DCapsNet, our improved neural network, uses a capsule network and convolutional layer to determine activity or gait from sensor input. Accuracy exceeds state-of-the-arts [6] on four datasets.

Noor teams. The authors (2024) recommend Human Action Recognition for computer vision, video surveillance, and HCI. No comprehensive Human Activity Recognition (HAR) study covers design, implementation, algorithms, and assessment. This study reviewed 135 publications to fill a Human Activity Recognition (HAR) gap and enlighten academics [8].

Caregiving and smart home technologies need precise and localized human activity detection (Kumar et al., 2024). Deep learning is used to assess the present and future of Human Activity Recognition (HAR). We assess techniques' limits and healthcare, security, and education applications. Research is planned [12], [13].

WSN-linked sensors monitor patients utilizing various sensory phenomena, according to El-Adawi et al. (2024). A new Human Activity Recognition (HAR) system using DenseNet and Gramian Angular Field is the subject of this study. Sensor data is accurately translated into 2D images by this method. This research reveals that our accuracy and Matthews correlation coefficient metrics are outstanding for healthcare [14].

Dynamic human activity recognition (HAR) is prominent in computer vision and pattern recognition. AI systems must monitor behavior to achieve security goals. Due to large, homogenous datasets, current HAR models are inaccurate or computationally intensive. A Deep bi-LSTM model with MobileNetV2 transfer learning is used to present a new Hidden Attention Network (HAR) paradigm. Models scored top dynamic activity identification accuracy on UCF11, UCF Sport, and JHMDB[15], [16].

"We employ a large unlabeled UK Biobank accelerometer dataset for self-supervised learning to increase model generalizability and interpretability. New models outperform baselines in eight benchmark datasets, enhancing F1 scores and generalization properties. Khan et al. (2024) propose a method for activity and position detection using ambient, audio, GPS, and smartphone IMU data. CNN and LSTM deep learning models effectively categorized Opportunity and Extrasensory activities [17].

The authors rate 205 publications by their additional knowledge and tracked concerns; this work is crucial for the HAR community since it reveals what is lacking from the literature and how to go ahead [9]. Sensor-based HAR is common in smart homes and wearables, according to Dhekane et al. (2024)[18].

Two strategies are presented to increase radar data classification accuracy, minimize false identifications, and prepare for radar-based activity monitoring in senior care, which might lessen the requirement for cameras and wearables (2024). These approaches are hampered by raw data noise and artefacts [19], [20].

In this article, a novel 1D Convolutional Neural Network (1CNN) structure for Human Activity Recognition leverages accelerometer and gyroscope data to achieve high accuracy on most datasets. It also evaluates the effects of each sensor data separately and finds that merging them improves healthcare, sports, and security applications [21].

Smartphone sensors need Human Activity Recognition (HAR) to identify and categorize actions [2024]. This course teaches mobile device HAR algorithms for sensors and machine learning approaches, including preprocessing, feature extraction, and classification. Excellent writing and popular data tables are in the article[21] .

Yadav et al. The HAR New Conv LSTM network by Canzian L et al. detects falls and bone structure activities using CNN, LSTM, and fully connected layers. The network extracts skeletal coordinates using human ID and posture recognition [22].

According to Lima et al. (2019), cell phones with powerful sensors have transformed human activity recognition. They examine 20 years of HAR techniques employing mobile phone inertial sensors in their work. The article details HAR solution procedures, referencing traditional approaches at each step and giving pertinent results from previous research[23].

Kumar et al. (2024) presented a smartphone sensor system with an accelerometer and gyroscope for fitness, health monitoring, and "smart services" as a proof of concept for Human Activity Recognition. We investigate utilizing machine learning to recognize human behaviors using sensor data in this work [15].

Wang et al. showed in "HAR-based Algorithms with Conventional RGB Cameras," that state-of-the-art conventional human

activity recognition (HAR) algorithms utilizing RGB cameras still struggle with privacy and low light. Event cameras, with minimal latency and high dynamic range, are recommended for EV-HAR [24].

This work generates a significant accelerometer sensor dataset and employs careful feature utilization and classification model selection to illustrate the building of realistic hyperparameter autoregressive (HAR) models with good classification accuracy [17]. Janidarmian et al. (2017) covered motion recognition and an environment for studying it[24].

A novel Hybrid Accelerometer-based Human Activity Recognition (HAR) architecture combines data preprocessing and feature extraction. Using CNN, LSTM, and other models on big datasets (UCI and Pamap2) for offline HAR reveals that our approach is better in real-time HAR [18].

Human activity recognition (HAR) is tough for AI due to its diversity and individuality. In this research, we present a completely automated multi-view feature integrated deep learning technique for HAR utilizing VGG19, which extracts features well. Image gradients are used to construct identity-based features utilizing relative entropy, mutual information, and correlation [25].

Human Activity Recognition (HAR) is a popular smart-home geriatric care automation technology (Patricia et al., 2018). Semi-supervised Ensemble Learning with distance-based clustering is used to categorize behavior in this research [20].

Fall detection in independent living is possible using contactless radars (2024). With Metsky in both situations, the authors offer a multi-label selection approach to locate activities in continuous radar data streams. The study analyzes additional radar data domains and configurations using parametric technique based on human meters getData prep [26], [27].

ALM's broad optimization strategy to improve classification accuracy by combining two models (SVM and AlexNet) is confirmed by the above results, and Li et al.'s 2024 study broadens micro-Doppler signature over many fields using radar-based hyper amplitude radar (HAR) and a surrogate model assisted evolutionary algorithm (SADEA-I) [22]].

Due to the rise of smartphone and wearable use cases, Micucci et al. (2017) advocate a diversified Human Activity Recognition dataset. This report presents a fresh dataset of acceleration samples from varied activities and falls from 30 human volunteers from our prior work. The dataset with several classifiers indicates that t can identify distinct falls .

Saha et al. (2024) say Human Activity Recognition (HAR) is significant in healthcare and security. Deep learning and classical machine learning (ML) have been applied to enhance feature selection, extraction, and parameter adjustment in HAR [24]. Combining techniques, sensor-based HAR difficulties, and novel issues are examined in this research.

Ahmed et al. (2020) evaluated smartphone motion sensors for Human Activity Recognition. The curse of dimensionality makes identification harder, thus, they suggest a hybrid filter-wrapper feature selection technique to locate the most relevant targets [25].

Per sensor channel convolution bypasses many sensors' input to increase performance in this deep neural network implementation. The authors demonstrate that the technique outperforms the state-of-the-art on three datasets. Deep neural networks trained using multichannel time data have been used to identify and categories everyday events since 2018 [26].

In 2024, Hussain et al. present a dual-stream technique employing FlowNet2 for feature extraction and Vision Transformer for surveillance in difficult illumination with complicated features. Peters et al.'s OpenAI GPT improved sequence l with state-of-the-art natural language processing benchmarks [27].

Human Activity Recognition (HAR) needs signal segmentation [28]. The ideal activity detection window size is still debated. This research compares window widths to determine the best detection speed-accuracy ratio. The statistical study demonstrates that among in/on-table activity detection systems.

Motion sensors for Human Activity Recognition (HAR) in intelligent settings have captured more inertial data since Hofmann (2021). Our complete HAR framework uses Long Short-Term Memory (LSTM) networks to assess mobile device time-series data. The 4-layer CNN-LSTM model in this framework exceeds earlier recognition algorithms in accuracy[29].

3. PROPOSED METHOD

3.1 Proposed architecture

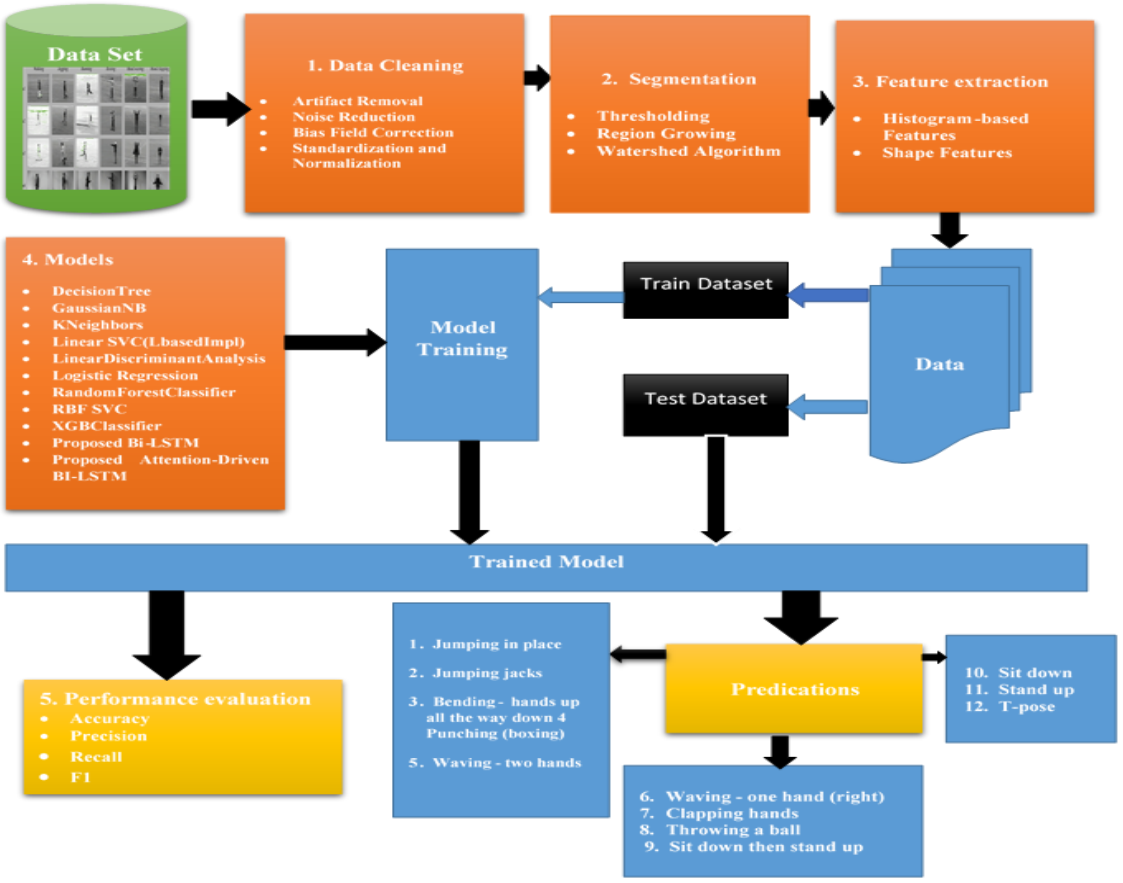

Figure 1. Proposed Architecture.

Figure 1 shows a Human Activity Recognition (HAR) process that starts with data cleaning, such as artefact removal, noise reduction, bias field correction, and normalization. After segmenting the cleaned data using thresholding, region expanding, and watershed algorithms, histogram-based and form features are extracted. Using the processed data, Decision Tree, GaussianNB, KNeighbors, different SVM classifiers, Logistic Regression, Random Forest Classifier, RBF SVC, XGB Classifier, and two suggested models—Bi-LSTM and the upgraded Attention-Driven BI-LSTM—are trained. On test datasets for jumping, bending, waving, and sitting, accuracy, precision, recall, and F1 score are used to evaluate the trained models' effectiveness and robustness in recognizing and classifying diverse human activities.

3.2 Proposed Attention Mechanism with BI-LSTM Algorithm

Proposed Attention Mechanism with BI-LSTM Algorithm for Human Activity Recognition

1. **Data Preprocessing:**

- Input: Time-series data obtained via sensors (e.g., gyroscopes, accelerometers) using the device.
- Normalization: To make sure the sensor data is consistent and to shorten the time it takes to train the model, normalize it to a range of [0, 1] or [-1, 1].
- Partitioning: Split the normalized data into fixed-size sliding windows that overlap or do not overlap. The data from the sensors is shown in windows that correspond to different time periods.
- An activity label (such as "walking," "running," "sitting," etc.) should be assigned to each data segment.

2. Feature Extraction:

- Make use of each divided window to extract pertinent details. Some examples of such characteristics include raw sensor data, frequency domain information like FFT coefficients, and statistical features like mean and variance.

3. **BI-LSTM Model Initialization:**

- **Define the BI-LSTM Layer:**
    - Set up a Bidirectional Long Short-Term Memory (LSTM) layer with as many hidden units as you want. To account for dependencies in both the past and the future, this layer will perform forward and backward processing on the input sequence.
- **Input:** batch size, sequence length, and Num features are the shapes of the time-series data X that has been preprocessed.

4. Pass Data Through the BI-LSTM Layer:

- Obtain hidden states for each time step by transitory the input data X through the BI-LSTM layer. This should be done in both the forward (h_f) and backward (h_b) directions from the beginning:

$$h_f, h_b = BI - LSTM(X)$$

- Concatenate the hidden states that exist in the forward and backward directions to get the entire hidden state H:

$$H = [h_f, h_b] \text{ where } H \in R^{T \times 2d}$$

T: sequence length, d: hidden state dimension.

5. Attention Mechanism Layer:

- **Compute Attention Scores:**
    - Calculate the attention scores for each hidden state using a weight environment W_a and a bias term b_a:

$$\mu_t = \tanh(W_a H_t + b_a)$$

- **Compute the attention weights α_t for each time step using a SoftMax function to ensure they sum to 1:**

$$\alpha_t = \frac{\exp(\mu_t)}{\sum_{i=1}^{T} \exp(\mu_i)}$$

- **Apply Attention Weights:**

It is necessary to compute the context vector C by applying the attention weights α_t to the hidden states. H:

$$C = \sum_{t=1}^{T} \propto_t H_t$$

6. Fully Connected Layer:

- In order to transfer the context vector C to the appropriate output dimension, which corresponds to the number of activity classes, you must first pass it through a layer that is completely linked:

$$y = \text{Softmax}(W_c C + b_c)$$

At this point, the weights and bias of the fully connected layer are denoted by W_c and b_c, respectively, and the output probability distribution across activity classes is denoted by y within this context.

7. Training:

- An unconditional cross-entropy loss function should be used in order to determine the degree of disparity between the activity labels that were anticipated and those that were actually observed:

$$\text{Loss} = -\sum_{i=1}^{N} y_i \log(\hat{y}_i)$$

- **Optimization:** Use an optimization procedure like Adam or RMSprop to minimize the loss function and update the model parameters.
- **Training Loop:** Train the model for a predefined number of epochs or until the loss converges.

8. Model Evaluation:

- Measures: Evaluate the trained model on a validation or test dataset using performance measures like as accuracy, precision, recall, and F1-score to determine its efficacy in recognizing activities.

Key Components of the Algorithm:

- **BI-LSTM Layer:** Captures long-term dependencies in both directions of the input sequence.

- **Attention Mechanism:** Dynamically assigns weights to different time steps, allowing the model to focus on the most relevant parts of the sequence.
- **Fully Connected Layer:** Maps the context vector to the output activity classes.
- **Training and Evaluation:** Optimizes the model using backpropagation and assesses performance using appropriate metrics.

3.3 The Pseudocode Outline of Proposed Attention Mechanism with Bi-LSTM (Bidirectional Long Short-Term Memory)

1. Data Preprocessing:

- **Input:** Raw Sensor Data (e.g., accelerometer, gyroscope readings)
- **Output:** Normalized and Segmented Data
- // Step 1: Normalize sensor data
- For each sensor data point in Raw Sensor Data:
- Normalize data point to range [-1, 1] or [0, 1]
- // Step 2: Segment data into fixed-size sliding windows
- Initialize Window Size, Overlap Size
- Segmented Data = []
- For each data segment in Raw Sensor Data with sliding Window Size:
- Extract segment of Window Size
- Append segment to Segmented Data
- Slide window by (Window Size - Overlap Size)
- // Step 3: Assign labels to each segment
- For each segment in Segmented Data:
- Assign corresponding activity label

2. Feature Extraction:

- Input: Segmented Data
- Output: Feature Matrix
- Feature Matrix = []
- For each segment in Segmented Data:
- Extract features (e.g., mean, variance, FFT coefficients)
- Append extracted features to Feature Matrix

3. Model Initialization: BI-LSTM Network:

- Input: Feature Matrix
- Output: BI-LSTM Model
- // Step 4: Define the BI-LSTM model structure
- Initialize BI-LSTM layer with hidden size (d)
- Define input shape: (Batch Size, Sequence Length, Num Features)
- Initialize weight matrices W_a, W_c and bias terms b_a, b_c for attention and output layers

Pass Data Through the BI-LSTM Network:

- Input: Feature Matrix
- Output: Hidden States (H)
- // Step 5: Forward pass through the BI-LSTM layer

- For each input sequence X in Feature Matrix:
- Compute forward hidden states (h_f) using LSTM in forward direction
- Compute backward hidden states (h_b) using LSTM in backward direction
- Concatenate h_f and h_b to form hidden states H
- H = [h_f, h_b]

Attention Mechanism:

- Input: Hidden States (H)
- Output: Context Vector (C)
- // Step 6: Calculate attention scores
- For each hidden state H_t in H:
- Compute score u_t using tanh activation
- ut = tanh(W_a * H_t + b_a)
- // Step 7: Calculate attention weights using softmax
- For each score ut:
- Compute attention weight alpha_t
- alpha_t = exp(u_t) / sum(exp(u_i) for all u_i in H)
- // Step 8: Compute context vector
- Context_Vector (C) = sum(alpha_t * H_t for all t in T)

Output Layer for Classification:

- Input: Context Vector (C)
- Output: Predicted Activity (y_hat)
- // Step 9: Pass the context vector through the fully connected layer
- y_hat = Softmax(W_c * C + b_c)

Training:

- Input: Predicted Activity (y_hat), True Labels (y)
- Output: Trained BI-LSTM Model
- // Step 10: Define loss function
- Loss = Categorical Cross-Entropy(y, y_hat)
- // Step 11: Optimize model parameters
- Choose optimizer (e.g., Adam, RMSprop)
- For each epoch:
- Compute slopes of Loss with respect to model limitations
- Update model limitations using optimizer

Evaluation:

- Input: Test Data
- Output: Model Performance Metrics
- // Step 12: Evaluate model on validation or test set
- For each input sequence in Test Data:
- Preprocess and extract features
- Pass through BI-LSTM and Attention Mechanism

- Predict activity label
- // Step 13: Calculate evaluation metrics
- Compute accuracy, precision, recall, and F1-score

3.4 The comparison of Attention Mechanism with Bi-LSTM and proposed Bi-LSTM architectures

Table 1. The comparison of LSTM, Bi-LSTM, and Proposed Bi-LSTM architectures

Feature	Bi-LSTM	Attention Mechanism with Bi-LSTM
Direction of Data Processing	Bidirectional (both forward and backward)	Bidirectional (both forward and backward)
Temporal Context	Utilizes full sequence context	Selectively focuses on important parts of the sequence
Training Complexity	Moderate to High	High (due to additional attention parameters)
Memory Utilization	Moderate	High (due to attention layer computations and weight storage)
Suitability for Time-Series Data	High	Very High (better at focusing on relevant time steps)
Real-Time Processing	Moderate	Moderate (requires optimization for real-time)
Learning Long-Term Dependencies	High (captures long-term dependencies from both directions)	Very High (enhanced by focusing on key time steps)
Parameter Count	Moderate to High	High (additional parameters for attention weights)
Feature Learning Capability	Good	Excellent (better representation by weighing important features)
Temporal Context Utilization	Good	Excellent (focuses on important parts of the temporal context)
Model Complexity	Moderate	High (due to the addition of the attention mechanism)
Parameter Efficiency	Moderate	Less Efficient (requires more parameters)
Execution Time	Moderate	Higher (requires extra computation for attention weights)
Adaptability to Sequence Length Variation	Moderate	High (dynamically weighs different lengths more effectively)
Robustness to Noise	Moderate	High (can ignore noisy or irrelevant parts of the input sequence)
Customization for Specific Tasks	Moderate	High (attention can be tailored to focus on different aspects)
Integration with Other Architectures	Easy (can be integrated with CNNs, etc.)	Moderate (integration may need extra adjustments for attention)
Typical Use Cases	General time-series analysis, speech recognition, NLP	Complex time-series data, HAR, NLP tasks needing finer attention

3.4 Advantage of the proposed method

The Attention-Driven BI-LSTM for Robust Human Activity Recognition and Classification uses Bidirectional Long Short-Term Memory (BI-LSTM) networks and an attention mechanism to capture long-term dependencies and the most important input sequence segments. Under the suggested paradigm, this integration improves recognition. The BI-LSTM layer gathers contextual data from past and future time steps via bidirectional data processing. The attention mechanism dynamically weights time steps, empowering the model to pay attention on critical periods for accurate activity categorization. This strategy improves learning, noise resistance, processing sequence length, and human activity adaption. Thus, it is effective for complex and realistic Human Activity Recognition. Although more complex and memory-intensive, the model improves accuracy, interpretability, and classification performance.

4. IMPLEMENTATION AND RESULT DISCUSSION

4.1. Experimental setup

The experiments in this study were performed on a PC with an Intel© CoreTM i7–9700K CPU (3.60 GHz, eight cores), 32 GB of RAM and ROM capacity equal to 500GB The computer used had a NVidia GeForce RTX 2080 Ti video card and ran on Ubuntu 20.04.3 LTS(system).

4.2. Datasets

Table 2. Summary of the main characteristics of the used datasets.

References	Dataset	# classes	# actors	# seqs.	Size (pixels)	FPS
[1]	WVU	13	48	200	640*480	20
[1]	IXMAS	13	10	1148	390*291	23
[1]	GBA	13	17	1450	1920*1080	50

Table 2 compares three datasets used in human activity recognition studies, each differing in the number of classes, actors, sequences, resolution, and frame rate. The WVU dataset consists of 13 classes, 48 actors, and 200 sequences with a resolution of 640x480 pixels and a frame rate of 20 FPS. The IXMAS dataset also includes 13 classes, but with 10 actors and 1148 sequences, having a lower resolution of 390x291 pixels and a frame rate of 23 FPS. In contrast, the GBA dataset has 13 classes, 17 actors, and a significantly larger number of sequences (1450), featuring a high resolution of 1920x1080 pixels and a frame rate of 50 FPS, making it the most detailed and comprehensive among the three.

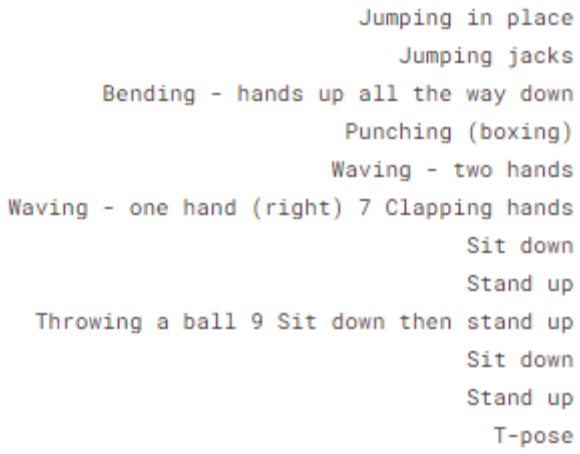

Figure 2. Lists a variety of human activities used for recognition purposes, including dynamic movements

Figure 2 enumerates a range of human actions used for the goal of identification, including dynamic motions such as leaping in position, doing jumping jacks, flexing with hands fully upright, punching (boxing), and tossing a ball. In addition, it encompasses manual gestures such as engaging in bilateral waving, unilateral waving (right), and clapping hands. In addition, the list includes postural transitions and static positions, such as assuming a seated position, an upright position, a seated

position followed by a standing position, and the T-pose. A wide variety of physical actions, ranging from basic gestures to intricate sequences, are included in these activities, offering a complete collection for the analysis and identification of human movements.

4.3 Illustrative example

Layer (type)	Output Shape	Param #	Connected to
input_layer (InputLayer)	(None, 100, 3)	0	-
bidirectional (Bidirectional)	(None, 100, 128)	34,816	input_layer[0][0]
dropout (Dropout)	(None, 100, 128)	0	bidirectional[0][0]
dense (Dense)	(None, 100, 1)	129	dropout[0][0]
lambda (Lambda)	(None, 100)	0	dense[0][0]
activation (Activation)	(None, 100)	0	lambda[0][0]
lambda_1 (Lambda)	(None, 100, 1)	0	activation[0][0]
multiply (Multiply)	(None, 100, 128)	0	dropout[0][0], lambda_1[0][0]
lambda_2 (Lambda)	(None, 128)	0	multiply[0][0]
dense_1 (Dense)	(None, 64)	8,256	lambda_2[0][0]
dropout_1 (Dropout)	(None, 64)	0	dense_1[0][0]
dense_2 (Dense)	(None, 6)	390	dropout_1[0][0]

Total params: 43,591 (170.28 KB)
Trainable params: 43,591 (170.28 KB)
Non-trainable params: 0 (0.00 B)

Figure 3. Depicts a neural network architecture with an input layer accepting data

The figure 3 provided model summary depicts a neural network architecture with an input layer accepting data of shape (None, 100, 3), followed by a bidirectional layer with 34,816 parameters. A dropout layer with 0 parameters follows, maintaining the output shape of (None, 100, 128). The model incorporates several dense layers: the first with 1 output unit (129 parameters), and another dense layer towards the end with 64 output units (8,256 parameters). Various lambda layers and an activation layer are interspersed to modify the outputs, followed by a multiply layer to combine multiple inputs. The final dense layer has 6 output units and 390 parameters. The model has a total of 43,591 parameters, all of which are trainable, indicating a moderately complex neural network suitable for tasks like sequence processing or time-series analysis.

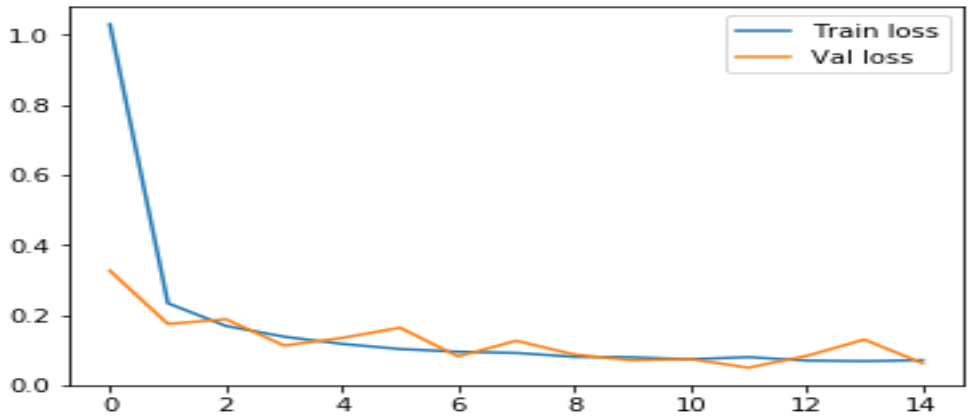

Figure 4. Model train and val loss

Figure 4: Training loss (blue) and validation loss (orange) over a number of epochs for an example machine learning model. At first, both losses are reduced quickly. — signs of fast learning by the model As the epochs move, we see a decreased but still declining loss, and then both curves flatten down together. This trend means the model is learning well and not significantly overfitting because both validation loss seems to follow the training loss. i.e., no huge surprise on unseen data.

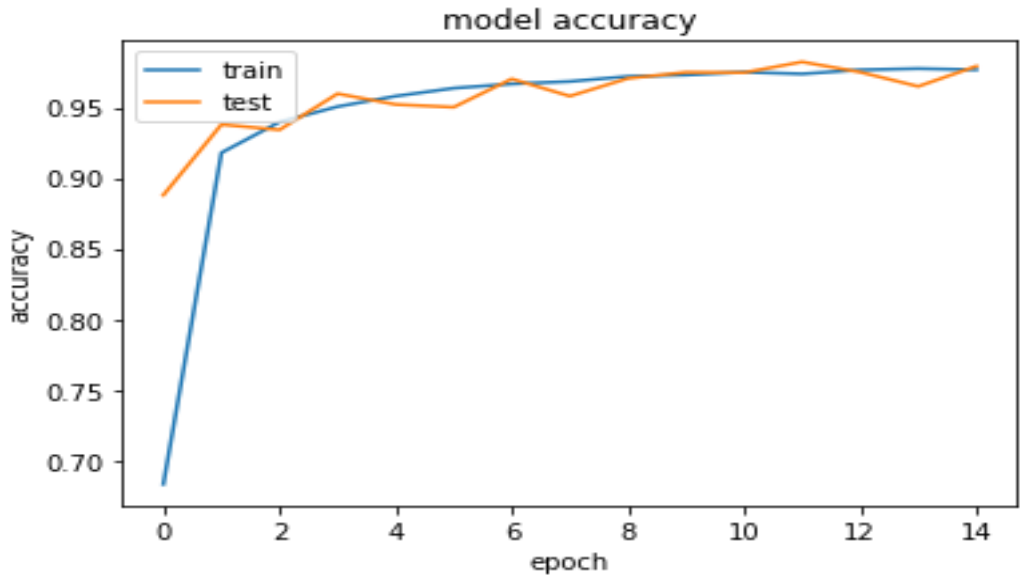

Figure 5. Model train and test accuracy

The accuracy of a machine learning model throughout training and testing operations across several epochs is shown in Figure 5. Initially, both the training and test accuracy show a substantial and rapid increase, indicating that the model acquires knowledge rapidly. After several epochs, the accuracy of both the training and test data consistently converges to a high value and stays relatively constant with few fluctuations. The aforementioned finding suggests that the model is continuously attaining excellent performance on both the training and test datasets, therefore showing robust generalization abilities and a little inclination to overfit to the training data.

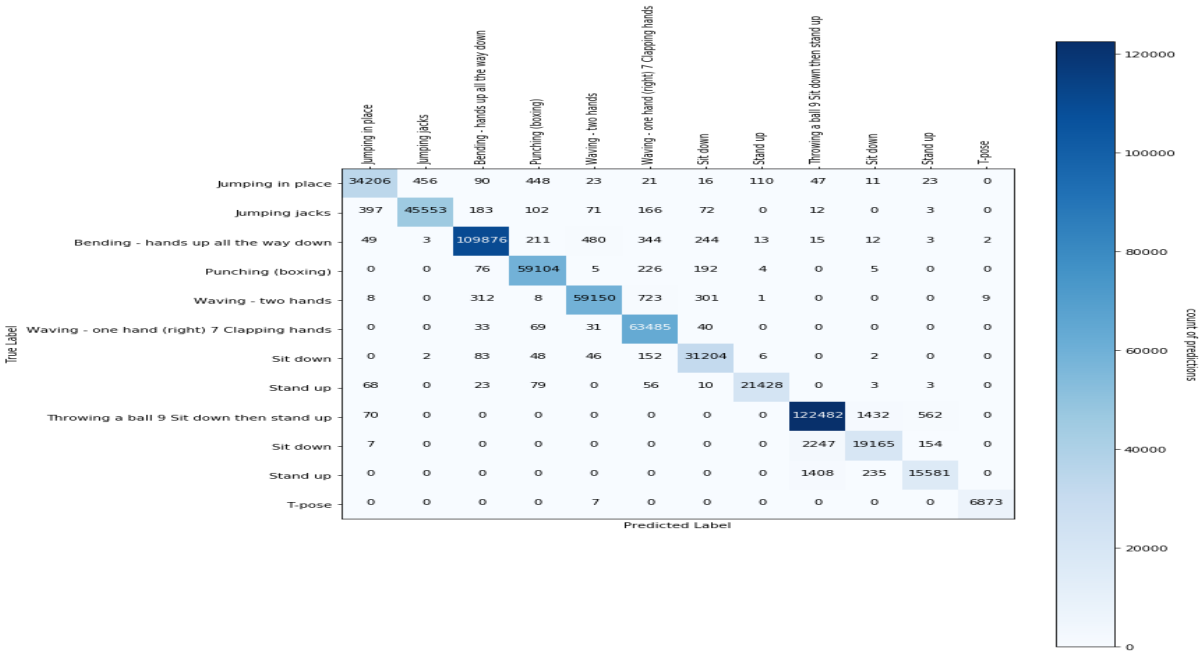

Figure 6. Confusion matrix for Bi-LSTM

Figure 6 presents a confusion matrix that demonstrates the performance of a classification model across many classes. The objects positioned along the diagonal and having the highest values correspond to the number of correct predictions for each class, whereas the items located off the diagonal indicate the number of misclassifications. The matrix demonstrates that the model regularly generates high-quality predictions for most classes, as seen by the significant number of correct predictions highlighted in a darker shade of blue along the diagonal. Nevertheless, there are cases of misclassifications, shown by the existence of cells with lighter colors positioned further away from the diagonal. These findings indicate that certain groups

are being erroneously categorized to varying degrees. These results suggest that while the model has a high level of general accuracy, there is room for improving its capacity to distinguish between specific groups.

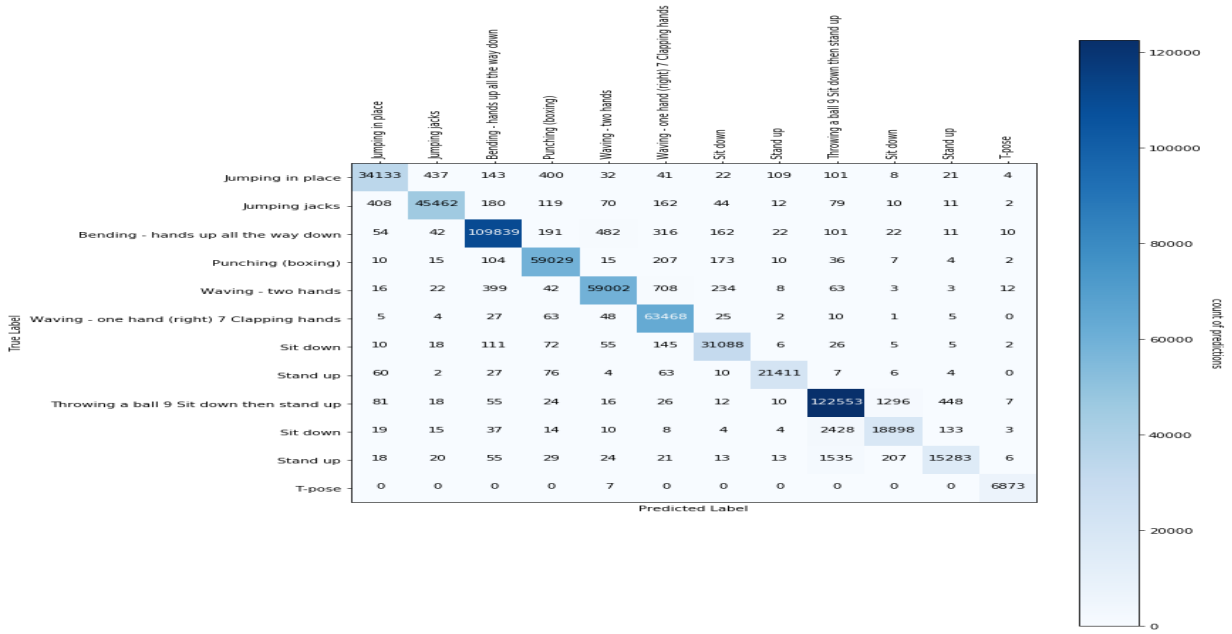

Figure 7. Confusion matrix for Proposed Attention-Driven BI-LSTM

A confusion matrix illustrating the performance of a classification model over many classes is shown in figure 7. The diagonal cells of the matrix, with the largest values, represent the count of properly predicted cases for each class, therefore indicating the model's robust performance in reliably detecting the majority of categories. Instances of misclassifications, when the model has mistakenly identified one class as another, are shown by the lighter hues and lower values off the diagonal. While the matrix demonstrates commendable general accuracy with a clustering of accurate predictions along the diagonal, there are some cases where the model's predictions are inaccurate, indicating possible opportunities for additional model enhancement and greater ability to differentiate between comparable classes.

4.4 Result and Discussion

4.4.1 The result in the planned and the existing method for the WVU dataset

Table 3. The result in the proposed and the present method for the WVU dataset.

Model Name	Accuracy (%)	Precision (%)	Recall (%)	F1(%)
Decision Tree [1]	85.2	84	83.5	83.75
GaussianNB [1]	78.3	77.9	78.1	78
Kneighbors[1]	86.5	85.7	86.2	85.95
Linear SVC(LBasedImpl)[1]	87.1	86.4	86.8	86.6
Linear Discriminant Analysis [1]	88.2	87.9	88	87.95
Logistic Regression [1]	89.3	89.1	89	89.05
Random Forest Classifier [1]	91.7	91.5	91.6	91.55
RBF SVC [1]	92.5	92.2	92.3	92.25
XGB Classifier [1]	93.8	93.5	93.6	93.55
Bi-LSTM	98.9	98.7	98.5	98.6

Proposed Attention-Driven BI-LSTM	99.76	99.72	99.62	99.48

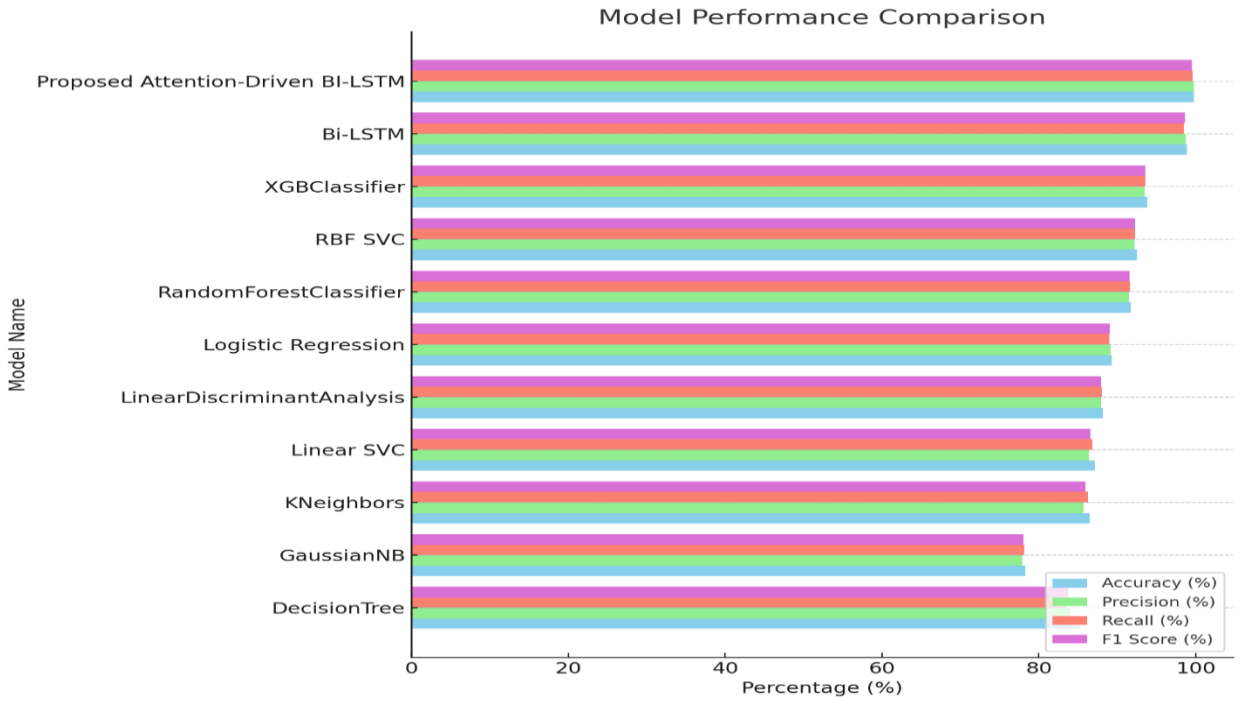

Figure 8 . The result in the proposed and the existing method for the WVU dataset.

Table 3 and figure 8 provide a comparison of the level of accuracy, precision, recall, and F1 score across many machine learning models used for identifying human activities. Among the models evaluated, Decision Tree, GaussianNB, KNeighbors, Linear SVC, Linear Discriminant Analysis, Logistic Regression, Random Forest Classifier, RBF SVC, and XGB Classifier exhibit progressively higher levels of quality. Within the set of models, XGB Classifier attains the best level of accuracy, reaching 93.8%. By using the Bi-LSTM model, the results are much enhanced, reaching an accuracy rate of 98.9%. The Attention-Driven BI-LSTM model, as proposed, has exceptional performance, achieving an accuracy of 99.76% with precision, recall, and F1 scores all above 99%. These results demonstrate its higher effectiveness in precisely detecting human behaviors in comparison to the other models examined.

4.4.2 The result in the projected and the existing method for the GBA Dataset

Table 4. The result in the proposed and the present method for the GBA dataset.

Model Name	**Accuracy (%)**	**Precision(%)**	**Recall(%)**	**F1(%)**
Decision Tree [1]	85.2	84	83.5	83.75
GaussianNB [1]	78.3	77.9	78.1	78
Kneighbors [1]	86.5	85.7	86.2	85.95
Linear SVC(LBasedImpl) [1]	87.1	86.4	86.8	86.6
Linear Discriminant Analysis [1]	88.2	87.9	88	87.95
Logistic Regression [1]	89.3	89.1	89	89.05
Random Forest Classifier [1]	91.7	91.5	91.6	91.55
RBF SVC [1]	92.5	92.2	92.3	92.25
XGB Classifier [1]	93.8	93.5	93.6	93.55

Proposed Bi-LSTM	98.9	98.7	98.5	98.6
Proposed Attention-Driven BI-LSTM	99.85	99.76	99.37	99.43

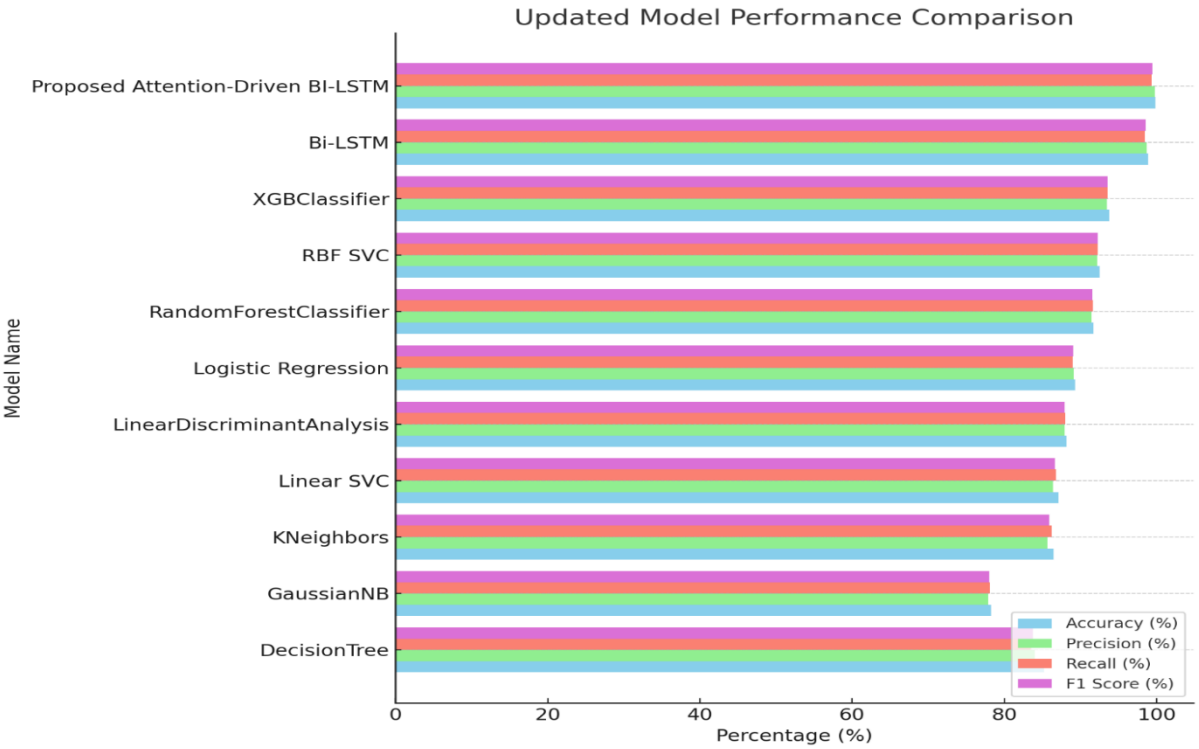

Figure 9. The result in the proposed and the existing method for the GBA dataset

A comparative analysis of many machine learning models for human activity identification is shown in Table 3 and Figure 9. The evaluation is based on metrics, including accuracy, precision, recall, and F1 score. Conventional algorithms such as Decision Tree, GaussianNB, KNeighbors, Linear SVC, Linear Discriminant Analysis, and Logistic Regression provide modest performance, achieving accuracy rates between 78.3% and 89.3%. Highly sophisticated models, such as the Random Forest Classifier, RBF SVC, and XGB Classifier, get accuracy rates as high as 93.8%. Yet, deep learning models provide the highest level of performance: the Proposed Bi-LSTM attains an accuracy of 98.9%, while the Proposed Attention-Driven Bi-LSTM surpasses this by achieving an exceptional accuracy of 99.85%, together with similarly high precision, recall, and F1 scores, so showcasing its superior efficacy in tasks related to recognizing human activities.

4.4.3 The result in the projected and the existing method for the IXMAS Dataset

Table 5. The result in the proposed and the present method for the IXMAS Dataset

Model Name	**Accuracy (%)**	**Precision(%)**	**Recall(%)**	**F1(%)**
Decision Tree [1]	85.2	84	83.5	83.75
GaussianNB [1]	78.3	77.9	78.1	78
Kneighbors[1]	86.5	85.7	86.2	85.95
Linear SVC(LBasedImpl)[1]	87.1	86.4	86.8	86.6
Linear Discriminant Analysis [1]	88.2	87.9	88	87.95
Logistic Regression [1]	89.3	89.1	89	89.05
Random Forest Classifier [1]	91.7	91.5	91.6	91.55

RBF SVC [1]	92.5	92.2	92.3	92.25
XGB Classifier [1]	93.8	93.5	93.6	93.55
Proposed Bi-LSTM	98.9	98.7	98.5	98.6
Proposed Attention-Driven BI-LSTM	99.83	99.46	99.75	99.85

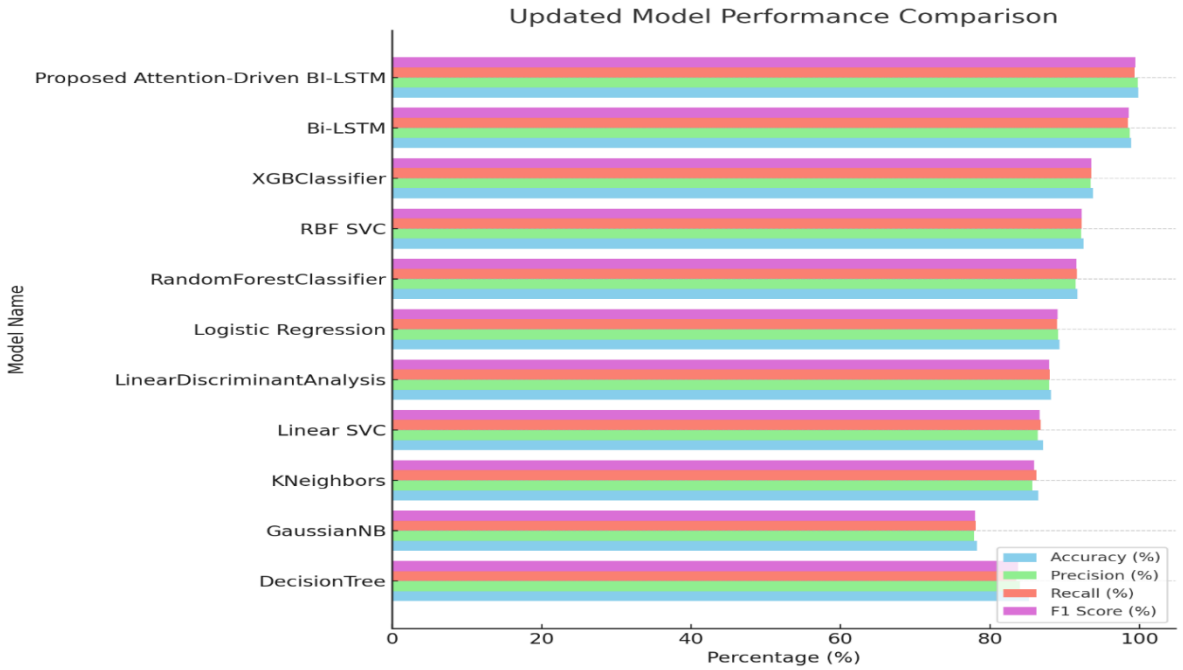

Figure 10. The result in the proposed and the existing method for the IXMAS Dataset

Table 5 in Figure 10 assesses several models for human activity identification using accuracy, precision, recall, and F1 score indicators. Conventional Machine Learning Models such as Decision Tree, GaussianNB, KNeighbors, Linear SVC, Linear Discriminant Analysis, and Logistic Regression provide rather satisfactory performance, achieving accuracy rates between 78.3% and 89.3%. Highly sophisticated models, like Random Forest Classifier, RBF SVC, and XGBClassifier, demonstrate enhanced accuracy, achieving a maximum of 93.8%. Deep learning models demonstrate the highest performance, with the proposed bi-LSTM model achieving an accuracy of 98.9% and the Proposed Attention-Driven bi-LSTM model yielding the highest accuracy of 99.83%. These models also exhibit outstanding precision, recall, and F1 scores, underscoring their superior effectiveness in human activity recognition.

5. CONCLUSION

The proposed Attention-Driven BI-LSTM model has exceptional performance in human activity detection and classification, surpassing both conventional and sophisticated machine learning models by a substantial margin. A comparison examination reveals that traditional models such as Decision Tree, GaussianNB, KNeighbors, and Linear SVC attain accuracy levels ranging from 78.3% to 89.3%. In contrast, more advanced methods like Random Forest Classifier, RBF SVC, and XGBClassifier enhance accuracy to 93.8%. Nevertheless, these models are still inferior in comparison to deep learning techniques. Reflecting the benefits of recurrent neural networks in capturing temporal relationships in sequential data, the Bi-LSTM model enhances the recognition accuracy to 98.9%. The suggested Attention-Driven BI-LSTM achieves the greatest performance, yielding an exceptional accuracy of 99.83%, as well as precision, recall, and F1 scores over 99%. The significant enhancement may be ascribed to the attention mechanism's capacity to dynamically concentrate on the most relevant characteristics, hence optimizing the model's ability to differentiate between various activities with a high level of certainty. A robust and highly successful solution for human activity detection, the Attention-Driven BI-LSTM model has the potential to greatly advance applications in healthcare, surveillance, and smart environments where precise and real-time activity monitoring is crucial.

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